

# Connections between Lyapunov inequalities and Subsolutions of an Isaacs equation for importance sampling

(joint work with P. Glynn and K. Leder)

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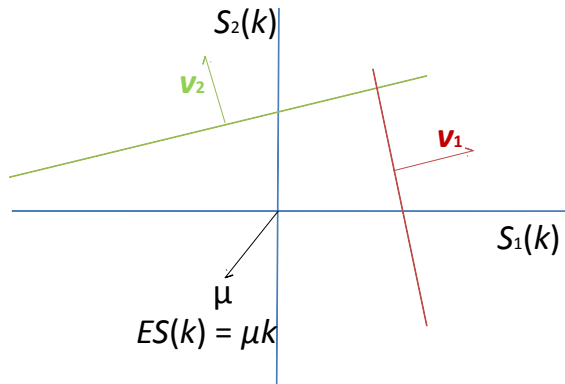
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# Outline

- 1 A Stylized Example
- 2 Example of an Isaacs Equation (Dupuis & Wang)
- 3 Isaacs Equation and Harmonic Functions
- 4 Lyapunov Inequalities and Subsolutions
- 5 Mollification
- 6 A Word on Tandem Networks
- 7 Conclusions

# Stylized Example

- State-space of a two dimensional random walk
- $A_n = \{s : v_2^T s \geq 1\}$  and  $B_n = \{s : v_1^T s \geq 1\}$



- Efficiently estimate as  $n \nearrow \infty$

$$u_n(0) = P_0[S_k/n \text{ hits } A \text{ OR } B \text{ Eventually}]$$

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- Note  $E Z_k^{(1)} = v_1^T \mu < 0$  and  $E Z_k^{(2)} = v_2^T \mu < 0$
- Assume there are  $\theta_1^*, \theta_2^* > 0$  such that

$$\begin{aligned} E \exp(\theta_1^* Z_k^{(1)}) &= 1 \quad \& \quad E \exp(\theta_2^* Z_k^{(2)}) = 1 \\ E[\exp(\theta_1^* Z_k^{(1)}) Z_k^{(1)}] &< \infty \quad \& \quad E[\exp(\theta_2^* Z_k^{(2)}) Z_k^{(2)}] < \infty \end{aligned}$$



# Large Deviations for the Stylized Example

- Then

$$\begin{aligned}u_n(x) &= P_x[W_n(t) \text{ hits } A \text{ OR } B] \\&\sim c_1 \exp(-n\theta_1^*(1 - v_1^T x)) + c_2 \exp(-n\theta_2^*(1 - v_2^T x)) \\&= \exp(-nh(x) + o(n))\end{aligned}$$

as  $n \nearrow \infty$ , where

$$h(x) = \min[\theta_1^*(1 - v_1^T x), \theta_2^*(1 - v_2^T x)].$$

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- $C_n(w) \approx \exp(-ng(w))$

$$\begin{aligned} 0 &\approx \min_{\lambda} \log E[e^{-\lambda^T X + \psi(\lambda) - n[g(w+Y/n) - g(w)]}] \\ &\approx \min_{\lambda} \max_{\beta} [-\beta^T (\lambda + \partial g(w)) + \psi(\lambda) - \mathbf{J}(\beta)] \end{aligned}$$

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- Subject to  $g(w) = 0$  on  $A \cup B$ .



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- $u_n(x) = 1$  on  $A \cup B$  and

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- Zero-variance sampler is:

$$P^*(Y_{k+1} \in dy | S_k = nx) = f(y) \frac{u_n(x + y/n)}{u_n(x)}$$

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- Approximate sampler  $u_n ( x ) \approx \exp ( -nh ( x ) )$

$$\begin{aligned} & \tilde{P} ( Y_{k+1} \in dy | S_k = nx ) \\ & \approx f ( y ) \exp ( -n [ h ( x + y/n ) - h ( x ) ] ) \\ & \approx f ( y ) \exp ( -\partial h ( x ) \cdot y ) \end{aligned}$$

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- But

$$1 = \int \tilde{P} ( Y_{k+1} \in dy | S_k = nx ) \implies \psi ( -\partial h ( x ) ) = 0$$

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- Equivalent to Isaacs equation with  $g(x) = 2h(x)$ .

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# The Second Moment of a State-dependent Estimator

- Consider any sampler

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$$r ( W_n(0), W_n(1/n) ) \dots r ( W_n(T_{AUB} - 1), W_n(T_{AUB}) )$$

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$$r ( W_n(0), W_n ( 1/n ) ) \dots r ( W_n ( T_{A \cup B} - 1 ), W_n ( T_{A \cup B} ) )$$

- Second moment of estimator

$$s(x) = E_x [ r(x, x + Y/n) s(x + Y/n) ]$$

subject to  $s(x) = 1$  for  $x \in A \cup B$ .

## Lemma

*B. & Glynn '07: Lyapunov inequality*

$$v(x) \geq E_x[r(x, x + Y/n)v(x + Y/n)]$$

*subject to  $v(x) \geq 1$  for  $x \in A \cup B$ . Then,  $v(x) \geq s(x)$ .*

- **How to use the result?** 1) Identify a change-of-measure, 2) use heuristic / approx. to force  $v(x) \approx u_n(x)^2$ .

# The Lyapunov Inequalities and Subsolutions

- Lyapunov function  $v(x) = \exp(-ng(x))$  &  $\lambda = -\partial g(x)/2$

$$1 \geq E[\exp(-\lambda^T Y + \psi(\lambda)) \exp(-n[g(x + Y/n) - g(x)])]$$

subject to  $g(x) \leq 0$  for  $x \in A \cup B$ . Then,  $v(x) \geq s(x)$ .

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- Expanding as  $n \nearrow \infty$  we get

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- Yields subsolution to the Isaacs equation (again smoothness)

$$\psi(-\partial g(x)/2) \leq 0 \text{ s.t. } g(x) \leq 0, x \in A \cup B$$

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# The Mollification

- Back to random walk example

$$\begin{aligned}h(x) &= \min[\theta_1^*(1 - v_1^T x), \theta_2^*(1 - v_2^T x)] \\ &= -\max[\theta_1^*(v_1^T x - 1), \theta_2^*(v_2^T x - 1)]\end{aligned}$$

NOT smooth...

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- Mollification:

$$\begin{aligned}h_\varepsilon(x) \\ = -\varepsilon \log[\exp(\theta_1^*(v_1^T x - 1)/\varepsilon) + \exp(\theta_2^*(v_2^T x - 1)/\varepsilon)]\end{aligned}$$

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- Implementation via mixtures:

$$\begin{aligned}-\partial h_\varepsilon(x) &= \theta_1^* v_1^T \frac{w_1^\varepsilon(x)}{w_1^\varepsilon(x) + w_2^\varepsilon(x)} + \theta_2^* v_2^T \frac{w_2^\varepsilon(x)}{w_1^\varepsilon(x) + w_2^\varepsilon(x)}, \\ w_1^\varepsilon(x) &= \exp(\theta_1^*(v_1^T x - 1)/\varepsilon), \\ w_2^\varepsilon(x) &= \exp(\theta_2^*(v_2^T x - 1)/\varepsilon).\end{aligned}$$

## Theorem (Dupuis & Wang '07)

Let  $g_{\varepsilon_n}(x) = 2h_{\varepsilon_n}(x)$  and assume that  $n\varepsilon_n \rightarrow \infty$  apply corresponding sampler. Then,

$$2\text{nd Moment of Est.} = \exp(-2nh(x) + o(n)).$$

# A Lyapunov Inequality

- Select  $\varepsilon_n = 1/n$

$$w_1(x) = \exp(n\theta_1^*(v_1^T x - 1))$$

$$w_2(x) = \exp(n\theta_2^*(v_2^T x - 1))$$

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- Mixture sampler from density  $\tilde{f}(y)$

$$\frac{\tilde{f}(y)}{f(y)} = \frac{w_1(x)}{w_1(x) + w_2(x)} \exp(\theta_1^* v_1^T y) + \frac{w_2(x)}{w_1(x) + w_2(x)} \exp(\theta_2^* v_2^T y)$$

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- Lyapunov function

$$v(x) = (w_1(x) + w_2(x))^2 \geq 1$$

for  $v_1^T x \geq 1$  OR  $v_2^T x \geq 1$ ... BOUNDARY CONDITION OK!

# A Lyapunov Inequality



$$\begin{aligned}v(x) &= [w_1(x) + w_2(x)]^2 \\w_1(x + Y/n) &= w_1(x) e^{\theta^* v_1^T Y} \\w_2(x + Y/n) &= w_2(x) e^{\theta^* v_2^T Y}\end{aligned}$$



# A Lyapunov Inequality



$$\begin{aligned}v(x) &= [w_1(x) + w_2(x)]^2 \\w_1(x + Y/n) &= w_1(x) e^{\theta_1^* v_1^T Y} \\w_2(x + Y/n) &= w_2(x) e^{\theta_2^* v_2^T Y}\end{aligned}$$



$$\begin{aligned}& E \frac{v(x + Y/n)}{v(x)} \frac{1}{\frac{w_1(x)}{w_1(x) + w_2(x)} e^{\theta_1^* v_1^T Y} + \frac{w_2(x)}{w_1(x) + w_2(x)} e^{\theta_2^* v_2^T Y}} \\&= E \frac{w_1(x) \exp(\theta_1^* v_1^T Y) + w_2(x) \exp(\theta_2^* v_2^T Y)}{w_1(x) + w_2(x)} = 1.\end{aligned}$$

- One can take  $\varepsilon = 1/n$  as mollification parameter

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- $\varepsilon = 1/n$  is the optimal choice (bounded coef. of variation)

$$2nd \text{ Moment} \leq (v_1(0) + v_2(0))^2 \leq cu_n(0)^2$$

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# Markovian Tandem Networks

- Consider a stable tandem network with  $d$  stations.
- $\beta = \#$  of bottlenecks (i.e. stations with maximum load)

## Theorem (B., Glynn and Leder '09)

*There is selection of mollification parameters that guarantees the coefficient of variation of the Dupuis-Sezer-Wang '07 sampler to be  $O\left(n^{2(d-\beta+1)}\right)$ .*

**Remark:** This guarantees *better* performance than solving the associated linear system of equations.

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- Subsolutions can be understood from the standpoint of Lyapunov inequalities.
- Lyapunov inequalities help understand the nature of mollification parameters.
- Lyapunov inequalities guided by subsolutions can strengthen the performance analysis.
- Better complexity of importance sampling vs. linear system for tandem rigorously validated.