

On Robust Risk Analysis

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We want to develop a systematic, data driven, approach for stress testing.

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- $P_{true}(\cdot)$ represents the **unknown** probabilistic law of X \leftarrow this is a problem.
- **How do we estimate $E_{true}(h(X))$ combining empirical sample and what-if scenarios in a meaningful way?**

Empirical Distributions and Stress Testing

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- Assume that the **REGULATOR** produces Y_1, \dots, Y_n i.i.d. copies from some r.v. Y . ← Think "WHAT-IF" distribution.
- **How do we incorporate the scenarios Y_1, \dots, Y_n as a form of stress testing?**

Incorporating Scenarios as Stress Testing

- **Step 1:** Define $Z_i = X_i$, for $i = 1, \dots, n$ and $Z_{n+j} = Y_j$ for $j = 1, \dots, n$ (put *ALL* scenarios X 's and Y 's together).

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- **Step 2:** Let

$$\mu_n(dx) = \frac{1}{n} \sum_{j=1}^n \delta_{\{X_j\}}(dx) \leftarrow \text{empirical. measure.}$$

$$\nu_n(dz) = \sum_{j=1}^{2n} \delta_{\{Z_j\}}(dz) w(j) \leftarrow \text{prob. measure.}$$

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- **Step 3:** Consider

$$\sup_{\nu_n(\cdot)} \{E_{\nu_n}(h(Z)) : d(\nu_n, \mu_n) \leq \delta\}.$$

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Natural Questions...

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- How to choose uncertainty region?
- How is this different from *distributionally* robust optimization?
- OK, so what's the new stuff here?

Choosing The Region and Connections to Distributionally Robust Optimization

- We advocate choosing Wasserstein's distance

$$d(v_n, \mu_n) = \min \left\{ \sum_{i,j} \pi(i,j) |Z_j - X_i|_2 : \pi_Z = v_n, \pi_X = \mu_n \right\}.$$

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- Robust Optimization: Ben-Tal, El Ghaoui, Nemirovski (2009).
- **It is crucial that $v_n(Y_j) > 0$: WE MUST VIOLATE ABSOLUTE CONTINUITY TO DO STRESS TESTING.**

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- Distributionally robust stress testing formulation is **NEW** here.
- **Main Contribution (to explain in the sequel):**

We explain how to optimally select δ and obtain confidence intervals.

- **Introducing Wasserstein's Profile Function**

$$\begin{aligned} & R_n(\gamma) \\ &= \min\left\{\sum_{i,j} \pi(i,j) |Z_j - X_i|_2 : \pi_Z = \nu_n, \pi_X = \mu_n, E_{\nu_n}(h(Z)) = \gamma\right\} \\ &= \min\left\{\sum_{i,j} \pi(i,j) |Z_j - X_i|_2 : \pi_X = \mu_n, E_{\pi}(h(Z)) = \gamma\right\}. \end{aligned}$$

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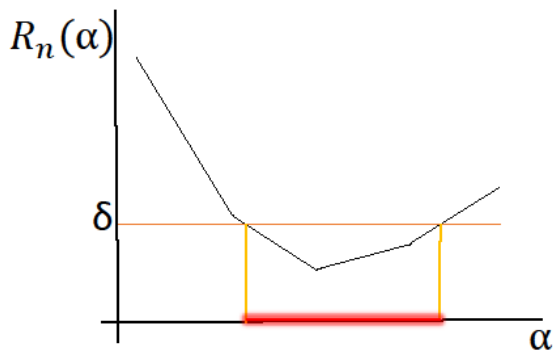
- Idea borrowed from Empirical Likelihood, Owen (1988).

Theorem (B. and Kang 2016)

Suppose $h(X)$ has a density $f(\cdot)$, $h(Y)$ has density $g(\cdot)$, and $E(h(X)^2 + h(Y)^2) < \infty$. Then under the null hypothesis, i.e. $H_0 : \gamma = E_{true}(h(X))$,

$$nR_n(\gamma) \rightarrow \kappa\chi_1^2.$$

How to Use The Wasserstein Profile Function?



$$P(R_n(\gamma) < \delta) \approx P(\chi^2 < \delta n / \kappa) = .95$$

Under H_0 we have $P(\gamma \in \text{Red interval}) \approx .95$

Incorporating Scenarios as Stress Testing

- Compute δ so that $P(\chi_1^2 \leq \delta n / \kappa) = .95$ and solve the LP

$$\max \sum_{j=1}^{2n} h(Z_j) w(j)$$

$$\sum_i \pi(i, j) \|X_i - Z_j\|_2 \leq \delta \quad \forall j$$

$$\sum_i \pi(i, j) = w(j) \quad \forall j, \quad \sum_j \pi(i, j) = \frac{1}{n} \quad \forall i$$

$$\pi(i, j) \geq 0 \quad \forall i, j$$

Theorem (B. and Kang 2016)

Suppose $H(X) = (h_1(X), \dots, h_d(X))$ has a density $f(\cdot)$, $H(Z)$ has density $g(\cdot)$, and $E\left(h_i(X)^2 + h_i(Y)^2\right) < \infty$. Then under the null hypothesis, i.e. $H_0: \gamma_i = E_{\text{true}}(h_i(X))$ for all i , then

- When $d = 1$,

$$nR_n(\gamma) \Rightarrow \kappa_1 \chi_1^2.$$

- When $d = 2$,

$$nR_n(\gamma) \Rightarrow \kappa_2 U^T \text{Var}(H(X)) U \text{ with } U \sim N(0, I).$$

- When $d \geq 3$,

$$n^{1/2 + \frac{3}{2d+2}} R_n(\gamma) \Rightarrow \kappa_d \left(\sqrt{U^T \text{Var}(H(X)) U} \right)^{1+1/(d+1)}.$$

Theorem (B. Kang and Murthy 2016)

Suppose you want to find β such that

$$\inf_{\beta} \sup_{d_C(P, \mu_n) \leq \delta} E_P[\|Y - \beta^T X\|_2^2],$$

then choosing a suitably chosen function $C(\cdot)$ the formulation turns out to be equivalent to generalized LASSO. And regularization parameter corresponds to δ . So one can choose it without using cross-validation.

Let's move to robust performance analysis of stochastic processes...

Theorem (B. & Murthy (2016))

Suppose X takes values on a Polish space \mathcal{S} . Let

$$C(x, y) : \mathcal{S} \times \mathcal{S} \rightarrow [0, \infty)$$

satisfy $C(x, x) = 0$, $C(x, y) \leq C(x, z) + C(z, y)$, and lower semicontinuous. Consider for A closed

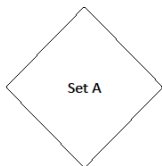
$$OPT = \sup P(Y \in A)$$

$$\text{s.t. } (X, Y) \text{ satisfies } : E(C(X, Y)) \leq \delta \text{ and } X \text{ follows } P_0.$$

Then,

$$OPT = P_0(X \in B(\delta)) = P_0\left(\inf_{y \in A} C(X, y) \leq 1/\lambda^*(\delta)\right).$$

Intuition for Multidimensional rv's

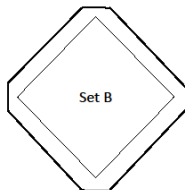


Question:
 $\max P(Y \in A)$
 $EC(X, Y) \leq \delta$
 X follows P_0

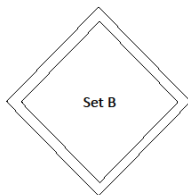
Answer:
 $P_0(X \in B)$

Shape of Set B
Depends on $C(\cdot)$

Cost:
 $C(X, Y) = |X - Y|_\infty$



Cost:
 $C(X, Y) = |X - Y|_2$



Conclusions: We Can Robustify in Great Generality!

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- New inference methodology designed to incorporate stress-testing scenarios.
- New robust performance analysis results for stochastic processes.
- Last word of caution: there is stuff that is just too bad to be robustified...

Not Everything Can be Robustified...

*Mexican
immigrant!*



**Now that we can robustify
in great generality...**

**Nothing can possibly go wrong...
Right?**